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Ti15WA (TimingServer)
#[ Keyword ][ VME @ ][ VSB @ ][ Mode ]
TIMING      0xe8ee2100 0xffffffff standalone

#[ Keyword ][ Input ] [ Freq./Div. ]
TI_INPUT    TI_FREQIN          0           // Input not used
TI_OUT_SET  TI_OSC_4MHz       TI_OUT1    2     2.5e-07   TI_POL_HIGH 0           // default width (2MHz) (=> TI_FREQIN(1), OK)
TI_OUT_SET  TI_OUT1          TI_OUT2    100    1e-06    TI_POL_HIGH 0           // (20000) (=> TI_SAMP(2), OK)
TI_OUT_SET  TI_OUT2          TI_OUT3    20000   5e-05    TI_POL_HIGH 0           // default width (20000) (=> TI_FRAME(3), OK)
TI_OUT_SET  TI_OUT3          TI_OUT4    32768   1        TI_POL_HIGH 0           // default width (0.6103515625) (=> TI_RUN(4), OK)
TI_OUT_SET  TI_OUT2          TI_OUT5    20000   5e-05    TI_POL_HIGH 19900 // default width (2MHz) (BNC DISCONNECTED(5),NO ???)

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Ti15WB (GxServer)
#[ Keyword ][ VME @ ][ VSB @ ][ Mode ]
TIMING      0xe8ee82100 0xffffffff slave

#[ Keyword ][ Input ] [ Freq./Div. ]
1 TI_INPUT  TI_FREQIN          2000000 // Frequency (2MHz)
2 TI_INPUT  TI_SAMPLING        100      // Division compared to TI_FREQIN (20000)
3 TI_INPUT  TI_FRAME          20000   // Division compared to TI_SAMPLING (1)
4 TI_INPUT  TI_RUN            32768   // Division compared to TI_FRAME (0.6103515625)
5 TI_INPUT  TI_FREQIN_SYNC    2000000 // Frequency (BNC DISCONNECTED ???)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT2    4000    3e-06   TI_POL_HIGH 100 // (2000000/4000=500)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT3    200     5e-07   TI_POL_HIGH 100 // (2000000/200=10000)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT4    200     3e-06   TI_POL_HIGH 100 // (2000000/200=10000)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT5    40000   1e-05   TI_POL_HIGH 0    // (2000000/40000=50)

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Example of suspension Timing board managed by GxServer (NorthEnd)

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Ti76B
#[ Keyword ][ VME @ ][ VSB @ ][ Mode ]
TIMING      0xe8ee2100 0xffffffff slave

#[ Keyword ][ Input ] [ Freq./Div. ]
TI_INPUT    TI_FREQIN          2500000 // Frequency (2.5MHz)
TI_INPUT    TI_SAMPLING        125      // Division compared to TI_FREQIN (20000)
TI_INPUT    TI_FRAME          20000   // Division compared to TI_SAMPLING (1)
TI_INPUT    TI_RUN            32768   // Division compared to TI_FRAME (0.6103515625)
TI_INPUT    TI_FREQIN_SYNC    2500000 // Frequency (2.5MHz)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT2    5000    3e-06   TI_POL_HIGH 125 // (2500000/5000=500)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT3    250     4e-07   TI_POL_HIGH 125 // default width (2500000/250=10000)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT4    250     3e-06   TI_POL_HIGH 125 // (2500000/250=10000)
TI_OUT_SET  TI_FREQIN_SYNC   TI_OUT5    50000   1e-05   TI_POL_HIGH 0    // (2500000/50000=50)

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Conversion Code - Chart																
DECIMAL	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
HEX	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
BINARY	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111

```

DOC
1110 1110 0010 1110 0010 0001 0000 0000
e   e   2   e   2   1   0   0

```

=> wrong number in the doc file

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Ti15WB
0Xe8ee82100

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SW2(DOC):

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+ 17 (+)
+ 18 (+)
+ 19 (+)
- 20
+ 21 (+)
- 22 (+)
- 23 (+)
- 24

```

SW1(DOC):

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+ 25
+ 26
+ 27 (+)
- 28
+ 29 (+)
- 30 (+)
- 31 (+)
- 32

```

```

11101000 11101000 0010000100000000
0010000100000000

```

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Ti15WA
0xe8ee2100
11101000 11101110 0010000100000000
0010000100000000

```

SW2:

+ 17

+ 18

+ 19

- 20

+ 21

- 22

- 23

- 24

SW1:

+ 25

+ 26

+ 27

- 28

+ 29

+ 30

+ 31

- 32