

Baffles and cryostat : Scattered light noise

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Hypotheses :

Distribution of scattered light vs scattering angle :

$$p(\theta) \approx \frac{\kappa}{\theta^2}$$
 For angles much larger than

$$\theta_g = rac{\lambda}{\pi w_0}$$

LSD of seismic motion :

$$\delta x(f) \approx 10^{-8} \text{ m/}\sqrt{\text{Hz}} \left[\frac{10 \text{ Hz}}{f}\right]^2$$





Spurious (noisy) phase modulation caused by the coupling :

$$\gamma = < TEM 00, s_5 >$$



 $\gamma = <\Phi, s_5 > = <\Phi, M_2P_2(m.s_3) > = <\Phi, M_2P_2[m.P_1(M_1\Phi)] >$

Coupling coefficient with TEM00 :

$$\gamma = e^{i\Delta(t)} \int m(\vec{x}) s_{D_1}(\vec{x}) s_{D_2}(\vec{x}) d\vec{x}$$

Expectation value :

$$\left\langle \gamma \gamma^* \right\rangle = \int m(\vec{x}) m(\vec{x}') * \left\langle s_{D_1}(\vec{x}) s_{D_1}(\vec{x}') * \right\rangle \left\langle s_{D_2}(\vec{x}) s_{D_2}(\vec{x}') * \right\rangle d\vec{x} d\vec{x}'$$

In terms of the speckle autocorrelation :

$$\Gamma \equiv \left\langle \gamma \gamma^* \right\rangle = \int m(\vec{x}) m(\vec{x}') * .C(D_1, \vec{x}, \vec{x}') .C(D_2, \vec{x}, \vec{x}') d\vec{x} d\vec{x}'$$



If $\delta x \ll \lambda$

PSD of SL-noise :

$$h(f) = \frac{\Gamma^{1/2}}{\sqrt{2}} \cos \theta \, \frac{\delta x(f)}{L}$$

Possible cases of coupling

Direct reflection from elementary spots IM→IM and EM→EM

1) Transmission EM→IM and IM→EM via inner baffle edge

3) Transmission EM→IM and IM→EM via spots on the inner edge

Direct reflection By reflecting element (α, β) D $r_C \sum$

Relevant parameters : -distance from mirror -Misaligment (α, β) -Mismatching r_C/D -Surface of the element

$\beta = 0$ $r_C = D$ $S = 10^{-6} \text{ m}^2$

D=0.9 m, *∆α*=0.46°

 $D=2.2 \text{ m}, \Delta \alpha = 0.19^{\circ}$ $D=5 \text{ m}, \Delta \alpha = 0.09^{\circ}$

 $D=1.5 \text{ m}, \Delta \alpha = 0.28^{\circ}$ $D=5 \text{ m}, \Delta \alpha = 0.09^{\circ}$





Case of input zone baffle \rightarrow End mirror $D=3000 \text{ m}, \Delta \alpha = 0.04^{\circ}$

ROC of the reflecting element



Conclusions for small reflecting defects : -Unsensitive to ROC of the zone -Sensitive to the distance -Sensitive to the pointing error

Summary

$$D = 0.9 \text{ m} : h(f) = 4.18 \ 10^{-26} \left[\frac{10 \text{ Hz}}{f}\right]^2 \text{ Hz}^{-1/2}, \ \Delta \alpha = 0.46^{\circ}$$
$$D = 1.5 \text{ m} : h(f) = 9.71 \ 10^{-26} \left[\frac{10 \text{ Hz}}{f}\right]^2 \text{ Hz}^{-1/2}, \ \Delta \alpha = 0.28^{\circ}$$
$$D = 2.2 \text{ m} : h(f) = 8.53 \ 10^{-26} \left[\frac{10 \text{ Hz}}{f}\right]^2 \text{ Hz}^{-1/2}, \ \Delta \alpha = 0.19^{\circ}$$
$$D = 5 \text{ m} : \ h(f) = 1.75 \ 10^{-25} \left[\frac{10 \text{ Hz}}{f}\right]^2 \text{ Hz}^{-1/2}, \ \Delta \alpha = 0.09^{\circ}$$
$$D = 3 \text{ km} : h(f) = 4.17 \ 10^{-25} \left[\frac{10 \text{ Hz}}{f}\right]^2 \text{ Hz}^{-1/2}, \ \Delta \alpha = 0.04^{\circ}$$



D=0.9 m , *Дα*=0.33°

$D=2.2 \text{ m}, \Delta \alpha=0.14^{\circ}$

 $D=1.5 \text{ m}, \Delta \alpha = 0.20^{\circ}$ $D=5 \text{ m}, \Delta \alpha = 0.07^{\circ}$

