

Tower	note	High Current -	Smooth Transition (2	Series resistor	Sensing	DC Actuation [mA/V]	DC Actuation [mA/V]	DC Sensing [V/A]	DC Sensing [V/A]	Filtering
		Low Noise	DAC per Coil)	[Ω] low noise	resistor [Ω] low noise	high current	low noise	high current	low noise	
		status @ VSR2								
<b>NE</b>										
up – down	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
right – left	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
Marionetta Left & Right	<b>still in Voltage mode (G=1.947)</b>							2		Actuation: pole@1Hz, zero@10Hz
<b>WE</b>										
up – down	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
right – left	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
Marionetta Left & Right	<b>still in Voltage mode (G=1.947)</b>							2		Actuation: pole@1Hz, zero@10Hz
<b>BS</b>										
up left – up right	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
down left – down right	Standard (last) CoilDriver	<b>YES</b>	Yes	300, 1200, 2400, 4800		~124	~3.1(LN1) ~0.82(LN2) ~0.41(LN3) ~0.2(LN4)	~10.8	327.5 (LN1)	Actuation (LN1): 2pole@0.9Hz, 2zero@9Hz Sensing (LN1): zero@3.4Hz, pole@97Hz
<b>NI</b>										
up – down		<b>YES</b>	NO	6k	3k	~195	0.33	10	6000	Actuation: pole@3Hz, zero@28Hz Sensing: zero@3.4Hz, pole@97Hz
right – left		<b>YES</b>	NO	6k	3k	~195	0.33	10	6000	Actuation: pole@3Hz, zero@28Hz Sensing: zero@3.4Hz, pole@97Hz
Marionetta Left & Right	<b>still in Voltage mode (G=1.947)</b>							2		Actuation: pole@1Hz, zero@10Hz
<b>WI</b>										
up – down		<b>YES</b>	NO	48k	24k	~195	0.04	10	48000	Actuation: pole@3Hz, zero@28Hz Sensing: zero@3.4Hz, pole@97Hz
right – left		<b>YES</b>	NO	48k	24k	~195	0.04	10	48000	Actuation: pole@3Hz, zero@28Hz Sensing: zero@3.4Hz, pole@97Hz
Marionetta Left & Right	<b>still in Voltage mode (G=1.947)</b>							2		Actuation: pole@1Hz, zero@10Hz
<b>MC</b>	<b>still in Voltage mode (G=1.947) + series resistor (47 ohm) (150 ohm for Lateral Coils)</b>	<b>NO</b>		47 or 150		~35		2		
<b>IB</b>	<b>still in Voltage mode (G=1.718) + series resistor (67 ohm)</b>	<b>NO</b>		67		~23		<b>ONLY VOLTAGE SENSING (gain = 200)</b>		Actuation: pole@3Hz, zero@28Hz Sensing: zero@0Hz, pole@1.6Hz
<b>PR</b>	<b>still in Voltage mode (G=1.947) + series resistor (91 ohm)</b>	<b>NO</b>		91		~19		2		Actuation: pole@1Hz, zero@10Hz
<b>OB</b>	<b>still in Voltage mode (G=1.958) + series resistor (30 ohm)</b>	<b>NO</b>		30		~58		2		Actuation: pole@3Hz, zero@28Hz